







# **RT6160B**

# Low Quiescent, High-Efficiency 3A ACOT® Synchronous Buck-Boost Converter with I<sup>2</sup>C Interface

# 1 General Description

The RT6160B is a high-efficiency, single-inductor, ACOT® (Advanced Constant On-Time) monolithic synchronous buck-boost converter that can deliver up to 3A output current from an input voltage range of 2.2V to 5.5V. It can regulate the digitally programmable output voltage from 2.025V to 5.2V, making it suitable for a wide range of input supply applications, regardless of whether the input voltage is lower, higher than, or equal to the output voltage. The ACOT® control architecture features outstanding line/load transient response, seamless transition between buck and boost modes, and provides stable operation with small ceramic output capacitors without the need for complicated external compensation.

The RT6160B features an  $I^2C$  interface for programmable output voltage, ultra-sonic mode control, VOUT DVS slew-rate adjustment, and device status monitoring. The target output voltage can also be switched through the external VSEL pin to perform DVS (dynamic voltage scaling), and the ramp-up slew-rate and ramp mode of DVS can be set by configuring the related registers.

The RT6160B operates with automatic PFM (Pulse Frequency Modulation) mode, featuring a low quiescent current design of typically  $3\mu A$ , maintaining high efficiency during light load operation.

At higher loads, the device automatically switches to a 2.2MHz fixed frequency control, effectively smoothing out the switching ripple voltage with small package filtering elements. The integrated low RDS(ON) power MOSFETs exhibit excellent efficiency under heavy load conditions. In shutdown mode, the supply current is typically  $0.1\mu A$ , contributing to reduce power consumption. The PFM mode can be disabled if a fixed frequency is required. The RT6160B is housed in a compact WL-CSP-15B 1.4x2.3 (BSC) package.

The recommended junction temperature range is  $-40^{\circ}$ C to 125°C, and the ambient temperature range is  $-40^{\circ}$ C to 85°C.

# 2 Features

- Automatic Seamless Mode Transition with Real Buck, Buck-Boost, and Boost Operation
- Input Voltage Range: 2.2V to 5.5V
- Output Voltage Range: 2.025V to 5.2V with Digitally Programmable Steps (25mV/steps)
- Default Output Voltage Settings:
  - Vout = 3.3V at VSEL = L
  - Vout = 3.85V at VSEL = H
- Maximum Continuous Output Current:
  - Up to 2.5A for V<sub>IN</sub> ≥ 2.5V, V<sub>OUT</sub> = 3.3V
  - Up to 3A for V<sub>IN</sub> ≥ 3V, V<sub>OUT</sub> = 3.3V
  - Up to 2A for V<sub>IN</sub> ≥ 3V, V<sub>OUT</sub> = 5V
- Up to 95% Efficiency (V<sub>IN</sub> = 3.8V, V<sub>OUT</sub> = 3.3V, ILOAD = 1A)
- 2µA Non-Switching Low Quiescent Current
- I<sup>2</sup>C Interface (up to 1MHz)
- Allow Dynamically-Voltage-Scaling Control
- Automatic PFM Mode and Forced PWM Mode Selection
- Ultra-Sonic Mode Operation
- Protections: OCP, UVLO, OTP, OVP, UVP
- 15-Ball WL-CSP Package

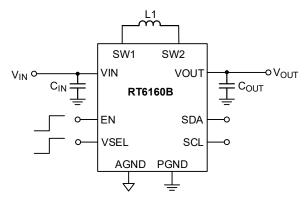
# 3 Applications

- Smartphones and Tablets
- Portable Devices
- · Wearable Devices
- System Pre-Regulators
- · Point-of-Load Regulators
- Wi-Fi Modules
- USB VCONN Supplies
- TWS Earbud Chargers

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# 4 Simplified Application Circuit



# **5 Ordering Information**



### Note 1.

Richtek products are Richtek Green Policy compliant and marked with (1) indicates compatible with the current requirements of IPC/JEDEC J-STD-020.

# **6 Marking Information**



9H: Product Code W: Date Code



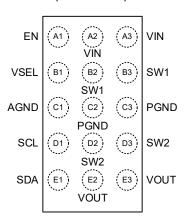
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# 7 Pin Configuration





WL-CSP-15B 1.4x2.3 (BSC)

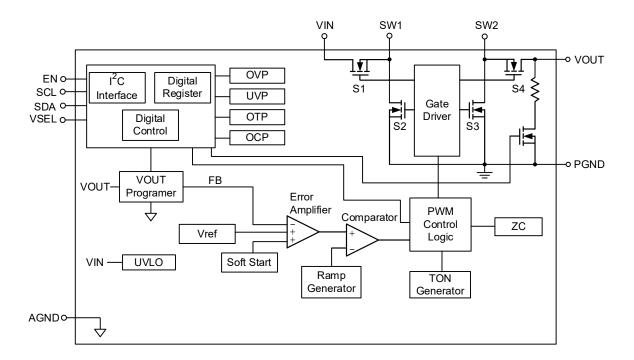
# **8 Functional Pin Description**

Pin No.	Pin Name	Pin Function
A1	EN	Enable control input. A logic-high enables the converter; a logic-low forces the device into shutdown mode.
A2, A3	VIN	Power input. The input voltage range is from 2.2V to 5.5V after the soft-start is finished. Connect input capacitors between this pin and PGND with minimal path. It is recommended to use a $10\mu\text{F}/6.3\text{V}/\text{X}5\text{R}/0402$ and a $0.1\mu\text{F}/6.3\text{V}/\text{X}5\text{R}/0201$ ceramic capacitor.
B1	VSEL	Voltage select pin. When this pin is grounded, VOUT is set by the VOUT1 register; when tied to logic-high, VOUT is set by the VOUT2 register.
B2, B3	SW1	Switching node 1. Connect to the inductor.
C1	AGND	Analog ground. All signals are referenced to this pin. Avoid routing high dV/dt AC currents through this pin.
C2, C3	PGND	Power ground. The low-side MOSFET is referenced to this pin. C <sub>IN</sub> and C <sub>OUT</sub> should be returned with a minimal path to these pins.
D1	SCL	I <sup>2</sup> C serial interface clock. This pin requires a pull-up resistor to I <sup>2</sup> C power supply.
D2, D3	SW2	Switching node 2. Connect to the inductor.
E1	SDA	I <sup>2</sup> C serial interface data. This pin requires a pull-up resistor to I <sup>2</sup> C power supply.
E2, E3	VOUT	Output voltage sense through this pin. Connect to the output capacitor. It is recommended to use two $22\mu F/10V/X5R/0603$ ceramic capacitors.

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# 9 Functional Block Diagram





# 10 Absolute Maximum Ratings

# (Note 2)

• Input Voltage, VIN	-0.3V to 6V
Output Voltage, VOUT	-0.3V to 6.2V
Switch Node Voltage, SW1, SW2	
DC	-0.3V to 6V
AC (<50ns)	-5V to 8.5V
Other I/O Pins Voltages (EN, VSEL, SCL, SDA)	-0.3V to 6V
• Power Dissipation, PD @ TA = 25°C	
WL-CSP-15B 1.4x2.3 (BSC)	1.88W
Package Thermal Resistance (Note 3)	
WL-CSP-15B 1.4x2.3 (BSC), θJA	53°C/W
• Junction Temperature	150°C
Lead Temperature (Soldering, 10 sec.)	260°C
Storage Temperature Range	−65°C to 150°C
• ESD Susceptibility (Note 4)	
HBM (Human Body Model)	2kV

- Note 2. Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions may affect device reliability.
- $\theta_{JA}$  is measured under natural convection (still air) at  $T_A = 25^{\circ}$ C with the component mounted on a high effectivethermal-conductivity four-layer test board on a JEDEC 51-7 thermal measurement standard.
- Note 4. Devices are ESD sensitive. Handling precautions are recommended.

# 11 Recommended Operating Conditions

# (Note 5)

• Input Voltage, V <sub>IN</sub>	2.2V to 5.5V
Output Voltage, Vout	2.025V to 5.2V
Output Current, Iout	0A to 3A
• Input Capacitance, CIN (Note 6)	5μF (Minimum)
Output Capacitance, Cout     (Note 6)	16μF (Minimum)
• Inductance, L	$0.39 \mu H$ to $0.56 \mu H$
Ambient Temperature Range	–40°C to 85°C
Junction Temperature Range	–40°C to 125°C

- **Note 5**. The device is not guaranteed to function outside its operating conditions.
- Note 6. Effective capacitance after DC bias effects have been considered.

RT6160B DS-02



# 12 Electrical Characteristics

( $V_{IN}$  = 3.6V,  $V_{OUT}$  = 3.3V,  $T_A$  =  $T_J$  = 25°C, unless otherwise specified.)

Parameter	Symbol	Test Conditions	Min	Тур	Max	Unit
VIN Supply Input Voltage	VIN		2.2	ŀ	5.5	>
Undervoltage-Lockout Rising Threshold	Vuvlo_r	VIN rising	2.11	2.14	2.19	>
Undervoltage-Lockout Falling Threshold	Vuvlo_f	VIN falling	2.02	2.05	2.08	>
Undervoltage-Lockout Hysteresis	Vuvlo_HYS			90	1	mV
Quiescent Current (Switching Current)	IQ_sw	V <sub>EN</sub> = V <sub>IN</sub> = 3.6V, I <sub>OUT</sub> = 0A		3	6	μΑ
Quiescent Current (Non-Switching Current)	IQ_NSW	VEN = VIN = 3.6V, IOUT = 0A, not switching		2	4	μΑ
Shutdown Current	ISHDN	$V_{EN} = 0V, V_{IN} = 3.6V$		0.1	1	μΑ
High-Level Input Current	Іін	VSCL = VSDA = VSEL = 1.8V, no pull-up resistor		I	0.1	μΑ
Low-Level Input Current	lıL	VSCL = VSDA = VSEL = 0V, no pull-up resistor		I	0.1	μΑ
Input Bias Current	IBIAS	VEN = 0 to 5.5V		-	0.1	μΑ
High-Side MOSFET Leakage Current	I_LK_H	VEN = 0V, VSW = 0V		1		μΑ
On-Resistance of High-Side MOSFET	RDSON_H			25	1	mΩ
On-Resistance of Low-Side MOSFET	RDSON_L			38		mΩ
Output Discharge Resistor	RDISCHG	VEN = 0V		5	ı	Ω
EN Input Voltage Rising threshold	VEN_R	VIN = 2.2V to 5.5V	1.2			V
EN Input Voltage Falling threshold	VEN_F	VIN = 2.2V to 5.5V			0.4	V
Input Voltage Logic-High (SCL, SDA, VSEL)	VIH		1.2			V
Input Voltage Logic-Low (SCL, SDA, VSEL)	VIL				0.4	V
Output Voltage Range	Vout_range		2.025	ı	5.2	V
Default Output Voltage (VSEL = L)	Vout_sel_l	V <sub>SEL</sub> = low		3.3		
Default Output Voltage (VSEL = H)	VOUT_SEL_H	VSEL = high		3.85		V
Output Voltage Accuracy (FPWM)	VOUT_ACC_ FPWM	Forced PWM operation	-1		1	
Output Voltage Accuracy (AUTO)	VOUT_ACC_ AUTO	Auto PFM operation	-1		3	%
Output Voltage Accuracy (USC)	Vout_acc_usc	Ultra-Sonic operation	-1		3	
Line Regulation	VLINE_REG	( <u>Note 7</u> )		0.5		%
Load Regulation	VLOAD_REG	( <u>Note 7</u> )		0.5		%

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Parameter	Symbol	Test Conditions	Min	Тур	Max	Unit
Maximum Continuous Output	lmax	$\begin{split} &\text{VIN} \geq 2.5\text{V, VOUT} = 3.3\text{V,} \\ &\text{L} = 0.47\mu\text{H, CIN} = 10\mu\text{F,} \\ &\text{COUT} = 44\mu\text{F} \qquad \underbrace{\left(\text{Note 8}\right)} \end{split}$	2.5			A
Current	IMAX	$V_{IN} \ge 3V$ , $V_{OUT} = 3.3V$ , $L = 0.47 \mu H$ , $C_{IN} = 10 \mu F$ , $C_{OUT} = 44 \mu F$ (Note 8)	3			ζ
High-Side Switch (Peak) Current Limit	Ішм_н	VIN = 3.6V, VOUT = 3.3V	4.5	5	5.5	Α
Low-Side Switch (Valley) Current Limit	I <sub>LIM_L</sub>	V <sub>IN</sub> = 3.6V, V <sub>OUT</sub> = 3.3V	4	4.5	5	Α
PFM to PWM Threshold Inductor Current	IL_T_PFM	VIN = 3.6V, VOUT = 3.3V, L = 0.47μH, CIN = 10μF, COUT = 44μF		0.3		А
		$\begin{aligned} &\text{VIN} = 3.3\text{V},  \text{VOUT} = 3.3\text{V}, \\ &\text{IOUT} = 0.1\text{A},  \text{L} = 0.47\mu\text{H}, \\ &\text{CIN} = 10\mu\text{F},  \text{COUT} = 44\mu\text{F}, \\ &\text{Auto PFM operation} \end{aligned}$		95		
F#:	η	$\begin{aligned} &V_{\text{IN}} = 3.3 \text{V},  V_{\text{OUT}} = 3.3 \text{V}, \\ &I_{\text{OUT}} = 1 \text{A},  L = 0.47 \mu \text{H}, \\ &C_{\text{IN}} = 10 \mu \text{F},  C_{\text{OUT}} = 44 \mu \text{F}, \\ &Forced PWM operation \end{aligned}$		94		%
Efficiency		VIN = 3.8V, VOUT = 3.3V, IOUT = 0.1A, L = 0.47 $\mu$ H, CIN = 10 $\mu$ F, COUT = 44 $\mu$ F, Auto PFM operation		94		
		VIN = 3.8V, VOUT = 3.3V, IOUT = 1A, L = 0.47 $\mu$ H, CIN = 10 $\mu$ F, COUT = 44 $\mu$ F, Forced PWM operation		95		
		$V_{\text{IN}} = 3.3V, \ V_{\text{OUT}} = 3.3V, \\ I_{\text{OUT}} = 0.1A, \ L = 0.47 \mu\text{H}, \\ C_{\text{IN}} = 10 \mu\text{F}, \ C_{\text{OUT}} = 44 \mu\text{F}, \\ \text{Auto PFM operation} \\ (\underline{\text{Note 7}})$		50		
Outrout Bingle Valters		VIN = 3.3V, VOUT = 3.3V, IOUT = 1A, L = 0.47 $\mu$ H, CIN = 10 $\mu$ F, COUT = 44 $\mu$ F, Forced PWM operation (Note 7)		20		, man
Output Ripple Voltage	VOUT_RIPPLE	$\begin{aligned} &\text{Vin} = 3.8\text{V},  \text{Vout} = 3.3\text{V}, \\ &\text{Iout} = 0.1\text{A},  \text{L} = 0.47\mu\text{H}, \\ &\text{Cin} = 10\mu\text{F},  \text{Cout} = 44\mu\text{F}, \\ &\text{Auto PFM operation} \\ &\frac{(\text{Note 7})}{} \end{aligned}$		25		- mV
		$VIN = 3.8V, \ VOUT = 3.3V, \\ IOUT = 1A, \ L = 0.47\mu H, \\ CIN = 10\mu F, \ COUT = 44\mu F, \\ Forced PWM \ operation \\ (\underline{Note \ 7})$		10		



Parameter	Symbol	Test Conditions	Min	Тур	Max	Unit	
Load Transient Response	VI OAD TR	Vin = 3.8V, Vout = 3.3V, Iout = 0.05A to 1A, tR = tF = $1\mu s$ (Note 7)	-100		100	mV	
Load Transient Nesponse	VLOAD_TR	$V_{IN} = 3.8V$ , $V_{OUT} = 3.3V$ , $I_{OUT} = 0.05A$ to 0.5A, $t_R = t_F$ = 1 $\mu$ s (Note 7)	-50		50	IIIV	
Line Transient Response	VLINE_TR	IOUT = 1A, VIN = 3V to 3.6V to 3V, tR = tF = $10\mu$ s (Note 7)	-50		50	mV	
Switching Frequency	fsw	Boost or Buck operation		2.2		MHz	
Switching Frequency Range	fsw_range	Forced PWM operation, IOUT = 100mA	0.5		3	MHz	
Switching Frequency at Ultra- Sonic Mode	fsw_usc	I <sub>OUT</sub> = 1mA	30			kHz	
Minimum On-Time	ton_min		20		60	ns	
Minimum Off-Time	toff_MIN		20		60	ns	
Output Voltage Rising Time Turn-On Rise Time	tR	Output voltage ramp to output voltage 95%, L = 0.47μH, CIN = 10μF, COUT = 44μF		300	1000	μs	
Enable Delay Time	tDLY_EN	Enable pin logic-high to output voltage ramp, L = 0.47μH, CIN = 10μF, COUT = 44μF		220	300	μs	
VSEL Delay Time	tdly_vsel	Delay between the rising edge of VSEL and the start of the DVS ramp		30		μs	
Output Undervoltage Rising Threshold	Vuvp_r			95		%	
Output Undervoltage Falling Threshold	VUVP_F			90		%	
		0x01, bit[1:0] = 00b	8.0	1	1.2		
Output Voltage Dynamic Voltage	DVC	0x01, bit[1:0] = 01b	2	2.5	3	,,,	
Scaling Slew Rate	DVSsR	0x01, bit[1:0] = 10b	4	5	6	V/ms	
		0x01, bit[1:0] = 11b	8	10	12		
Over-Temperature Protection Threshold	Тотр	(Note 7)	140	150	160	°C	
Over-Temperature Protection Hysteresis	Totp_hys	( <u>Note 7</u> )		20		°C	

Note 7. Guaranteed by design.

**Note 8**. The device can sustain the maximum recommended output current. Users must verify that the thermal performance of the end application can support the maximum output current.

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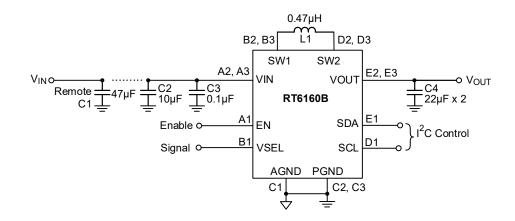


# 12.1 I<sup>2</sup>C Characteristics

Parameter	Symbol	Test Conditions	Min	Тур	Max	Unit
Logic Output Threshold Voltage (SCL, SDA, VSEL)	Vo_l2C				0.4	V
I <sup>2</sup> C Work Voltage	VINT_I2C			1.8		V
Input Current Each IO Pin	IIN_I <sup>2</sup> C		-10		10	μА
SDA Setup Time	tsu;dat		70			ns
		Standard mode			100	kHz
SCL Clock Frequency	fscL	Fast mode			400	
		Fast mode plus			1000	
		Standard mode	4.7			
Bus Free Time between Stop and Start	tBUF	Fast mode	1.3			μS
and Start		Fast mode plus	0.5			
		Standard mode	4.7			
(Repeated) Start Hold Time	thd;sta	Fast mode	0.6			μS
		Fast mode plus	0.26			
	tsu;sta	Standard mode	4.7			
(Repeated) Start Setup Time		Fast mode	0.6			μS
		Fast mode plus	0.26			
	thd;dat	Standard mode	0.1			ns
SDA Data Hold Time		Fast mode	0.1			
		Fast mode plus	0.1			
	tsu;sto	Standard mode	4			μs
STOP Condition Setup Time		Fast mode	0.6			
		Fast mode plus	0.26			
	tvd;ack	Standard mode			3.45	
SDA Valid Acknowledge Time		Fast mode			0.9	μS
Time		Fast mode plus			0.45	
		Standard mode	250			ns
SDA Setup Time	tsu;dat	Fast mode	100			
		Fast mode plus	50			
		Standard mode	4.7			μS
SCL Clock Low Period	tLOW	Fast mode	1.3			
		Fast mode plus	0.5			
		Standard mode	4			
SCL Clock High Period	thigh	Fast mode	0.6			μS
		Fast mode plus	0.26			



# 13 Typical Application Circuit



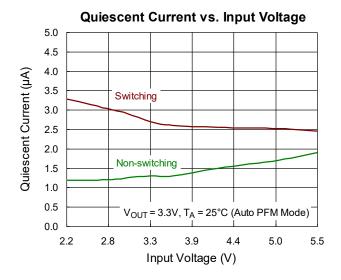
**Table 1. Recommended Components Information** (Note 9)

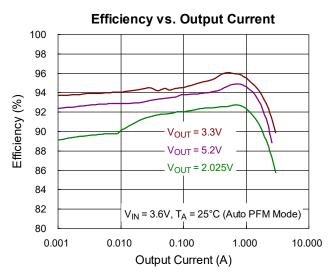
Reference	Part Number	Description	Package	Manufacturer
C1 ( <u>Note 10</u> )	GRM32ER61C476KE15	47μF/16V/X5R	1210	Murata
C2	GRM155R60J106ME15	10μF/6.3V/X5R	0402	Murata
C3 ( <u>Note 11</u> )	GRM033R60J104KE19	0.1μF/6.3V/X5R	0201	Murata
C4	GRM188R61A226ME15	22μF/10V/X5R	0603	Murata
L1	XFL4015-471MEC	0.47μΗ	4x4x1.5mm	Coilcraft

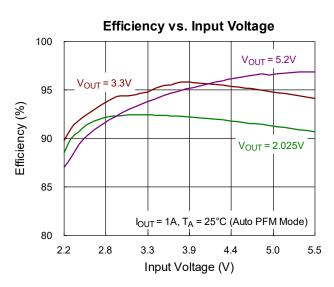
- Note 9. All the input and output capacitors are the suggested values, referring to the effective capacitances, subject to any derating effects, such as DC bias.
- Note 10. The decoupling capacitor C1 is a remote Cout capacitor. C1 is optional. The device is designed to operate with a DC supply voltage in the range of 2.2V to 5.5V. If the input supply is more than a few centimeters from the device, it is recommended to add some bulk capacitance to the ceramic bypass capacitors. A 47 µF electrolytic capacitor is a typical selection for the bulk capacitance.
- Note 11. The decoupling capacitor C3 is recommended to reduce any high-frequency components on the VIN bus. C3 is optional and used to filter any high-frequency components on the VIN bus.

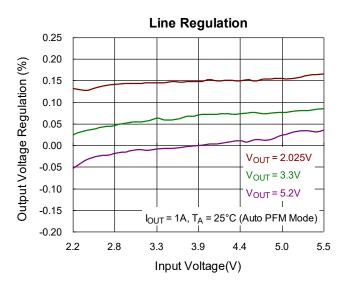


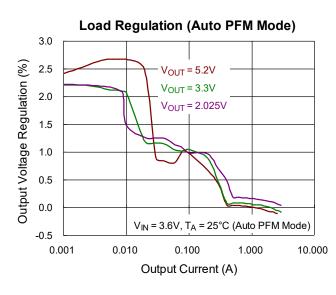
# 14 Typical Operating Characteristics

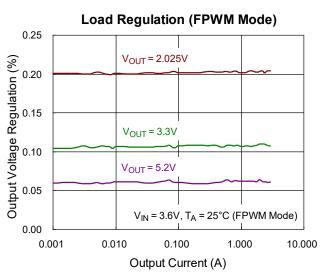




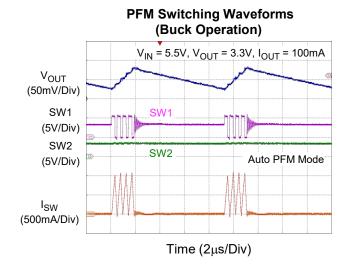


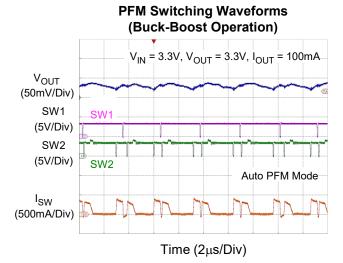


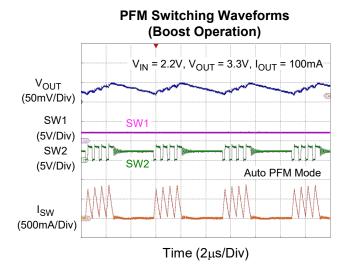


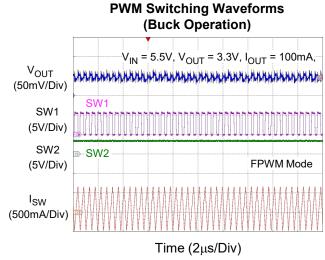


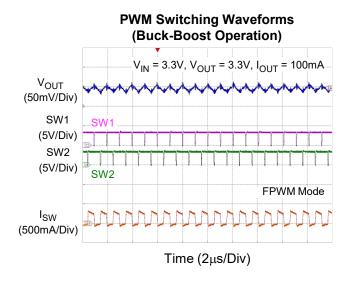


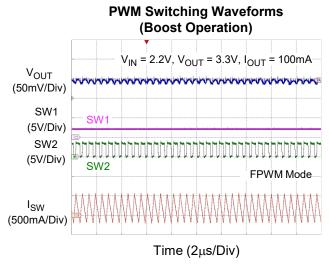












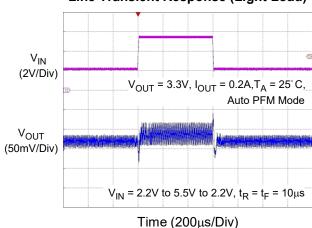
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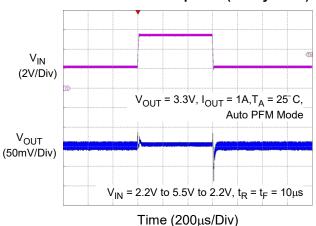
is a registered trademark of Richtek Technology Corporation.



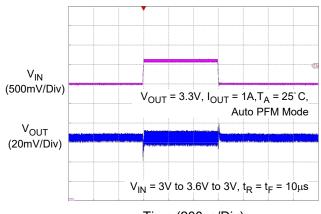
# **Line Transient Response (Light Load)**



### Line Transient Response (Heavy Load)

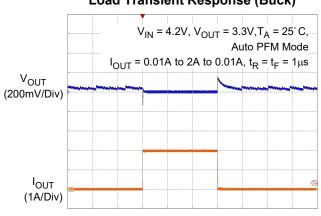


**Line Transient Response (SPEC Condition)** 



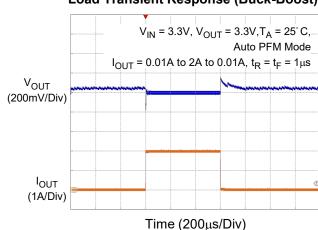
Time (200µs/Div)

Load Transient Response (Buck)

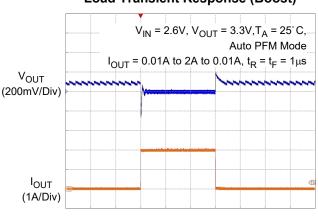


Time (200µs/Div)

### **Load Transient Response (Buck-Boost)**



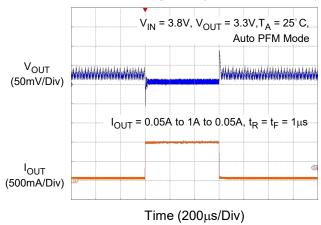
**Load Transient Response (Boost)** 



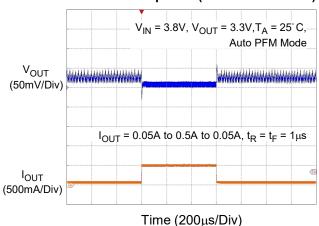
Time (200µs/Div)



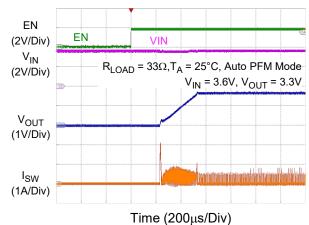
# Load Transient Response (SPEC Condition1)



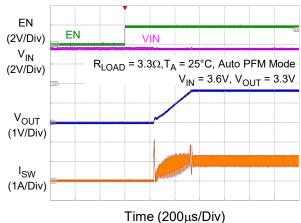
### Load Transient Response (SPEC Condition2)



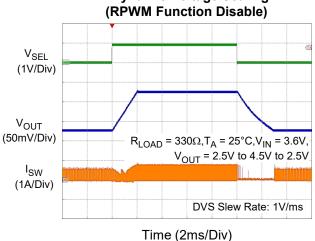
## Start-Up Waveforms (Light Load)



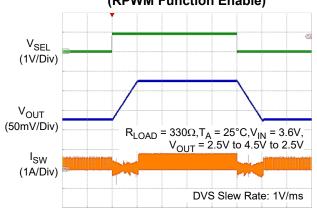
Start-Up Waveforms (Heavy Load)



Dynamic Voltage Scaling



Dynamic Voltage Scaling (RPWM Function Enable)



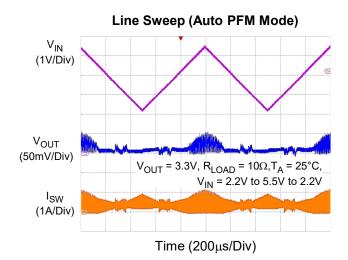
Time (2ms/Div)

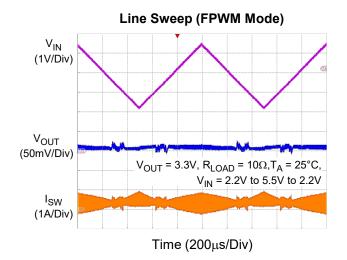
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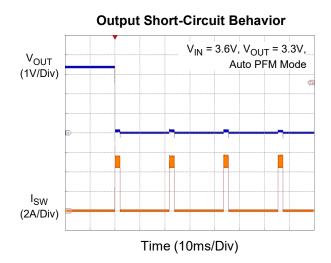
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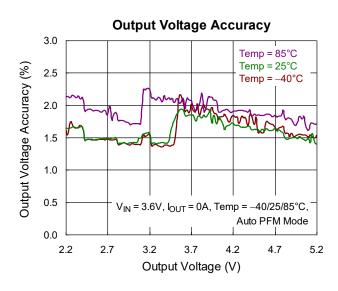
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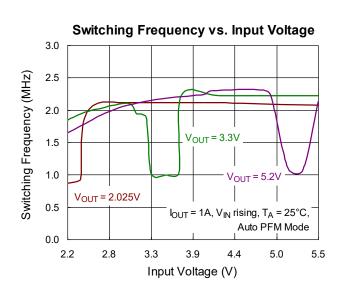


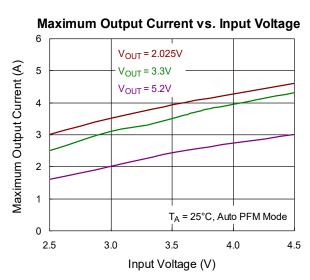












RT6160B DS-02



# 15 Operation

The RT6160B adopts a high-efficiency, single-inductor, ACOT<sup>®</sup> (Advanced Constant On-Time) mode control mechanism designed to achieve a fast transient response and good stability with low-ESR ceramic capacitors.

The ACOT<sup>®</sup> control scheme uses a virtual inductor current ramp generated inside the IC to replace the ramp normally provided by the output capacitor's ESR. The internal ramp signal and other internal compensations are optimized for low-ESR ceramic output capacitors.

# 15.1 Buck Operation

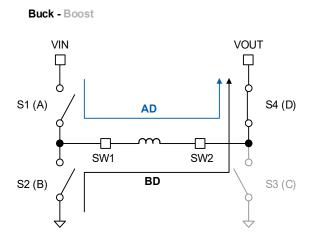


Figure 1. Buck Operation

When V<sub>IN</sub> > V<sub>OUT</sub>, the device operates like a buck converter. In steady-state buck-mode operation, the on-time pulse turns on the high-side switch S1, while S4 remains on, and the inductor current ramps up linearly. After the on-time period, the high-side switch S1 is turned off, and the synchronous rectifier switch S2 is turned on, while S4 remains on, and the inductor current ramps down linearly.

### 15.2 Boost Operation

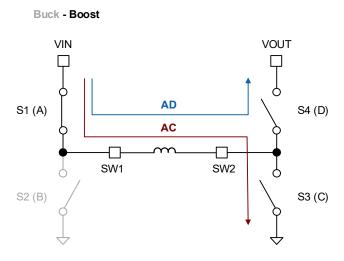


Figure 2. Boost Operation

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When V<sub>IN</sub> < V<sub>OUT</sub>, the device operates like a boost converter. In boost mode under light load conditions, the on-time pulse turns on the S3 switch to maintain a constant on-time, while S1 remains on, and the inductor current ramps up linearly. After the on-time period, the S3 switch is turned off, and the synchronous rectifier switch S4 is turned on for a certain time, while S1 remains on, and the inductor current ramps down linearly. When the inductor current drops to zero, S4 will turn off. As the loading current increases, the device operates in CCM (continuous conduction mode), and the switches are modulated to maintain the desired output voltage. When the feedback signal is less than the reference value, the device turns on S3, while S1 remains on. After the off-time one-shot is cleared, the inductor current ramps up linearly. Then, the off-time one-shot turns on S4, while S1 remains on, and the inductor current ramps down linearly.

### 15.3 Buck-Boost Operation

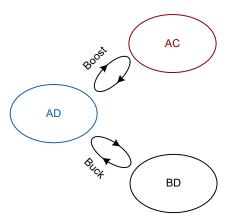


Figure 3. Buck-Boost Operation

When  $V_{IN} \approx V_{OUT}$ , all four transistors switch continuously, and the device operates in buck-boost mode. In buck-boost mode under light-load conditions, the device turns on switches S1 and S3, allowing the inductor current to increase linearly until it reaches the target peak-current level. When the inductor current reaches the peak-current level, switches S1 and S4 are turned on for a constant time, allowing the inductor current to decrease linearly. Afterward, switches S2 and S4 are turned on to ensure the inductor decreases to zero. At light-load conditions, the frequency increases as the load increases. Once the loading current is large enough, the converter will transition from boundary-conduction mode to continuous conduction mode. Furthermore, when VIN is close to VOUT in CCM, the switching frequency will decrease to half of the nominal switching frequency, and the device will maintain the output voltage tracking the target VOUT.



# 16 Application Information

#### (Note 13)

The basic RT6160B application circuit is shown in the Typical Application Circuit. External component selection is determined by the maximum load current and begins with the selection of the inductor value and operating frequency followed by CIN and COUT.

#### 16.1 Soft-Start

An internal current source charges an internal capacitor to build the soft-start ramp voltage. During the soft-start period, the device sets  $\overline{PG}$  to "1" until VOUT reaches 99% of its set voltage.

The rise time of the output voltage changes with the application circuit and the operating conditions. The rise time of the output voltage increases if:

- The load current is large
- · The output capacitance is large

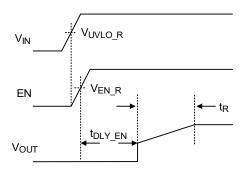


Figure 4. Soft-Start Sequence

### 16.2 Enable

The RT6160B provides an EN pin as an external chip enable control to enable or disable the device. If the EN voltage is held below the logic-high threshold ( $VEN_R$ ), switching is inhibited, even if the VIN voltage is above the UVLO rising threshold voltage ( $VUVLO_R$ ). If the EN voltage is held below 0.4V, the converter will enter shutdown mode; in this state, the converter is disabled, and all registers are reset to their default values. During shutdown mode, the supply current can be reduced to ISHDN ( $I\mu A$  or below). It is recommended that the VIN voltage should be higher than the VIN rising threshold voltage ( $VUVLO_R$ ) first. Then, when the EN voltage rises above the logic-high threshold ( $VEN_R$ ), the device will turn on, enabling switching and initiating the soft-start sequence.

Note that there is a  $100\mu s$  delay time to allow  $I^2C$  read/write operations when the EN pin goes above the logic-high threshold.

#### 16.3 **VSEL**

- When VSEL = L, the default output voltage is 3.3V, which can be programmed via Address 0x04[6:0] in the VOUT1 register.
- When VSEL = H, the default output voltage is 3.85V, which can be programmed via Address 0x05[6:0] in the VOUT2 register.

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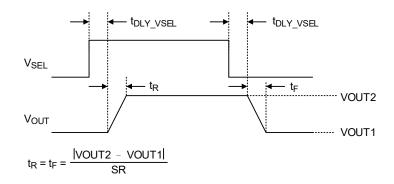


Figure 5. DVS Control the VSEL Pin

The SR in Figure 5 is the slew rate set by the (DVS Slew Rate) bits in the CONTROL register.

# 16.4 Auto Pulse Frequency Modulation Mode

In order to save power and improve efficiency at low loads, the buck/boost converter operates in PFM (Pulse Frequency Modulation) mode as the inductor drops into DCM (Discontinuous Current Mode). The switching frequency is proportional to the load to achieve output voltage regulation. When the load increases and the inductor current becomes continuous again, the buck/boost converter automatically switches back to PWM fixed frequency mode. Additionally, the RT6160B will enter DSLP (Deep Sleep) mode to achieve low input quiescent current at no load. Auto PFM Mode is the default mode.

#### 16.5 Forced Pulse Width Modulation Mode

The switching frequency is forced into PWM mode operation. In this mode, the inductor current is in CCM (Continuous Current Mode) and the voltage is regulated by PWM. To enable Forced-PWM operation, set the FPWM bit in the Control register to 1.

#### 16.6 Ultra-Sonic Mode

In order to avoid operational noise issues, the switching frequency is always designed to be higher than 30kHz, even when there is no load at the output. To enable Ultra-Sonic Mode operation, set the Ultra-Sonic Mode bit in the Control register to 1.

# 16.7 Ramp-PWM Function

If you want the device to operate in Auto PFM mode and ensure that dynamic voltage scaling ramps the output voltage up and down in a controlled manner, enabling the Ramp-PWM function is very useful. In Ramp-PWM mode, the device operates in forced-PWM when it ramps from one output voltage to another during dynamic voltage scaling. If the device operates in Auto PFM mode and Ramp-PWM is not enabled, the device cannot control the ramp from a higher output voltage to a lower output voltage, because in Automatic PFM/PWM mode, the device cannot sink current.

To enable the Ramp-PWM function, set the RAMP bit in the Control register to 1.

To disable the Ramp-PWM function, clear the RAMP bit in the Control register to 0.



## 16.8 Dynamically Voltage Scaling Control

RT6160B supports a programmable slew-rate control feature for increasing and decreasing the output voltage, also known as DVS (Dynamically Voltage Scaling). The ramp slew-rate can be set to 1V/ms, 2.5V/ms, 5V/ms, or 10V/ms through bit 1 and bit 0 of the control register. Moreover, the operation mode during the DVS region can be adjusted through control register bit 2. When the device operates in Auto PFM/PWM mode, if bit 2 is set to 1, the device will change to Forced PWM mode operation during the DVS region and revert to auto PFM/PWM mode after reaching the target output voltage. The device will keep auto PFM/PWM mode during the DVS region if bit 2 of the control register is set to 0

#### 16.9 Output Discharge

The device actively discharges the output when the EN pin is low.

#### 16.10 Vour Selection

The RT6160B has a programmable VouT range from 2.025V to 5.2V with a 25mV resolution. The output voltage can be set by the VOUTX register bits, and the output voltage is given by the following equation:

Vout = 2.025V + VOUTX [6:0] x 25mV

For example:

if VOUTX [6:0] = 110011 (51 decimal), then:

 $VOUT = 2.025V + 51 \times 25mV = 2.025V + 1.275V = 3.3V$ .

The RT6160B also has an external VSEL pin to select VOUT1 (0X04) or VOUT2 (0X05). Pulling VSEL high selects VOUT2, and pulling VSEL low selects VOUT1. Upon power-on reset (POR), VOUT1, and VOUT2 are reset to their default voltages.

### 16.11 Power-Good Comparator

When a power-not-good condition occurs, the device sets the  $\overline{PG}$  bit in the Status register to 1. The device clears the  $\overline{PG}$  bit to 0 if you read the Status register when a power-good condition exists.

#### 16.12 Auto-Zero Current Detector

The auto-zero current detector circuit senses the SW1 and SW2 waveforms to adjust the zero current threshold voltage. When the current of the low-side MOSFET decreases to the zero current threshold, the low-side MOSFET turns off to prevent negative inductor current. In this way, the zero current threshold can be adjusted for different conditions to achieve better efficiency.

#### 16.13 Load Disconnect

During device shutdown, the input is disconnected from the output. This prevents any current flow from the output to the input or from the input to the output.

# 16.14 PWM Frequency and Adaptive On-Time Control

The on-time can be roughly estimated by the following equation:

$$t_{ON} = \frac{V_{OUT}}{V_{IN}} \times \frac{1}{f_{SW}}$$

where fsw is nominally 2.2MHz.

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### 16.15 Inductor Selection

Choosing an inductor value will affect transient response, ripple, and other performance aspects. The RT6160B recommends a nominal inductance value of 0.47 µH to achieve optimal performance.

The inductor value and operating frequency determine the ripple current according to a specific input and output voltage. The ripple current  $\Delta I_L$  increases with higher VIN and decreases with higher inductance.

$$\Delta I_{L} = \left(\frac{V_{OUT}}{f_{SW} \times L}\right) \times \left(1 - \frac{V_{OUT}}{V_{IN}}\right)$$

Having a lower ripple current reduces not only the ESR losses in the output capacitors but also the output voltage ripple. High frequency with small ripple current can achieve the highest efficiency operation. However, it requires a large inductor to achieve this goal.

For the ripple current selection, the value of  $\Delta I_L$ , which is IMAX multiplied by 0.3, will be a reasonable starting point.

The largest ripple current occurs at the highest VIN. To guarantee that the ripple current stays below the specified maximum, the inductor value should be chosen according to the following equation:

$$L = \left(\frac{V_{OUT}}{f_{SW} \times \Delta I_{L(MAX)}}\right) \times \left(1 - \frac{V_{OUT}}{V_{IN(MAX)}}\right)$$

The inductor's current rating (causing a 40°C temperature rise from a 25°C ambient) should be greater than the maximum load current, and its saturation current should be greater than the short circuit peak current limit.

### 16.16 Input Capacitor Selection

The steady-state and transient response performance also depend on input voltage stability. The RT6160B recommends using at least a 10μF input capacitor to prevent input voltage instability during operation.

It is recommended to place the capacitor as close as possible to the VIN and GND pins of the IC. If the input supply is located more than a few centimeters from the device, adding some bulk capacitance to the ceramic bypass capacitors is recommended.

A 47µF electrolytic capacitor is a typical selection for the bulk capacitance.

# 16.17 Output Capacitor Selection

The ripple voltage is an important index for choosing the output capacitor. This portion consists of two parts: one is the product of ripple current with the ESR of the output capacitor, and the other part is formed by the charging and discharging process of the output capacitor. The output capacitor is selected based on the output ripple, which is calculated using the equation below:

$$\Delta V_{OUT} = \Delta V_{ESR} + \Delta V_{OUT_{CAP}}$$

$$\Delta V_{ESR} = I_{C_{RMS}} \times R_{C_{ESR}}$$

$$\Delta V_{OUT_{CAP}} = \frac{I_{OUT} \times Duty}{f_{SW} \times C_{MIN}}$$

User can choose a capacitor using the equation to meet the system's ripple specifications. It is recommended to use at least two 22µF capacitors to match the application's requirements for VOUT ripple and stability performance.



### **Table 2. Protection Trigger Condition and Behavior**

The RT6160B features several protections, such as OCP, OVP, UVLO, OTP and UVP. The table below describes the protection actions.

Protection Type	Threshold Refer to Electrical Spec.	Deglitch Time	Protection Method	Reset Method
OCP ( <u>Note 12</u> )	I <sub>L</sub> > 5A	0	Turn off boost LG or Turn off buck UG	IL < 4.5A
UVLO	V <sub>IN</sub> < 2.08V (maximum)	0	Turn off all	V <sub>IN</sub> > 2.17V (maximum)
OTP	TEMP > 150°C	0	Turn off all	OTP Hysteresis = 20°C
OVP	Vout > 6V	0	Turn off all	Vout < 5.6V
UVP	Vout < 0.9 x Vout_Target	2ms	Turn off all	Vout > 0.95 x Vout_Target

Note 12. Turn off all switches when OCP event occurs and is continuing for 2ms.

#### 16.18 Overcurrent Protection

The Overcurrent Protection (OCP) function is implemented by UGATE and LGATE. When the inductor current reaches the UGATE current limit threshold, the high-side MOSFET will be turned-off. The low-side MOSFET turns on to discharge the inductor current until the inductor current drops below the LGATE current limit threshold. After the UGATE current limit is triggered, the maximum inductor current is determined by the inductor current rising rate and the response delay time of the internal network.

### 16.19 Input Undervoltage-Lockout Protection

In addition to the EN pin, the RT6160B also provides enable control through the VIN pin. If VEN rises above VEN R first, switching will still be inhibited until the VIN voltage rises above VUVLO R. This ensures that the internal regulator is ready, preventing operation with not-fully-enhanced internal MOSFET switches. After the device is powered up, if the VIN voltage goes below the UVLO falling threshold voltage (VUVLO F), switching will be inhibited. If the VIN voltage rises above the UVLO rising threshold (VUVLO R), the device will resume switching.

### 16.20 Over-Temperature Protection

When the junction temperature exceeds the OTP threshold value, the IC will shut down the switching operation. Once the junction temperature cools down and is lower than the OTP lower threshold, the converter will automatically resume switching. When the device detects an over-temperature condition, it sets the TSD bit in the Status register to 1. The device clears the TSD bit to 0 if you read the Status register when the junction temperature of the device is less than 130°C.

### 16.21 Overvoltage Protection

When the VOUT pin is floating, the device will trigger overvoltage protection to prevent the output voltage from exceeding critical values. If the output reaches the OVP threshold, the device will regulate the voltage to maintain it at this threshold value.

### 16.22 Undervoltage Protection

The RT6160B provides Hiccup Mode for Undervoltage Protection (UVP). When the Vout voltage drops below 90% of the target Vout, the UVP function will be triggered to shut down switching operation. If the UVP condition remains for a period, the RT6160B will retry to build up the output voltage automatically. When the UVP condition is removed, the converter will soft-start to the target voltage and resume normal operation.

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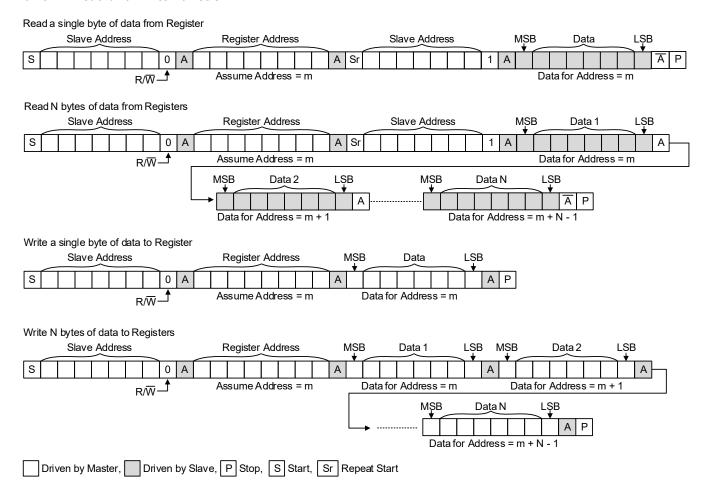
# 16.23 I<sup>2</sup>C Interface

The following table shows the RT6160B slave address 0x75(7bit).

RT6160B I <sup>2</sup> C Slave Address (75H)			
MSB	LSB	R/W bit	R/W
111010	1	1/0	EB/EA

The I<sup>2</sup>C interface bus must be connected to a  $2.2k\Omega$  resistor to the power node and independently connected to the processor. The I<sup>2</sup>C timing diagrams are listed below.

### 16.23.1 Read and Write Function



# 16.23.2 I<sup>2</sup>C Waveform Information

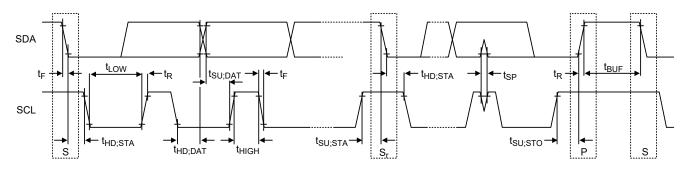


Figure 6. I<sup>2</sup>C Read and Write Stream and Timing Diagram



#### 16.24 Thermal Considerations

The junction temperature should never exceed the absolute maximum junction temperature T<sub>J</sub>(MAX), listed under Absolute Maximum Ratings, to avoid permanent damage to the device. The maximum allowable power dissipation depends on the thermal resistance of the IC package, the PCB layout, the rate of surrounding airflow, and the difference between the junction and ambient temperatures. The maximum power dissipation can be calculated using the following formula:

 $PD(MAX) = (TJ(MAX) - TA) / \theta JA$ 

where  $T_{J(MAX)}$  is the maximum junction temperature,  $T_A$  is the ambient temperature, and  $\theta_{JA}$  is the junction-to-ambient thermal resistance.

For continuous operation, the maximum operating junction temperature indicated under Recommended Operating Conditions is  $125^{\circ}$ C. The junction-to-ambient thermal resistance,  $\theta_{JA}$ , is highly package dependent. For a WL-CSP-15B 1.4x2.3 (BSC) package, the thermal

resistance,  $\theta_{JA}$ , is 53°C/W on a standard JEDEC 51-7 high effective-thermal conductivity four-layer test board. The maximum power dissipation at  $T_A$  = 25°C can be calculated as below:

 $P_{D(MAX)} = (125^{\circ}C - 25^{\circ}C) / (53^{\circ}C/W) = 1.88W$  for a WL-CSP-15B 1.4x2.3 package.

The maximum power dissipation depends on the operating ambient temperature for the fixed  $T_{J(MAX)}$  and the thermal resistance,  $\theta_{JA}$ . The derating curve in <u>Figure 7</u> allows the designer to see the effect of rising ambient temperature on the maximum power dissipation.

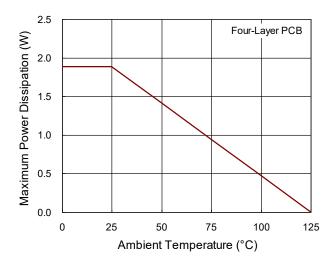


Figure 7. Derating Curve of Maximum Power Dissipation

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### 16.25 Layout Considerations

For the best performance of the RT6160B, the following layout guidelines must be strictly followed:

- The input capacitor must be placed as close as possible to the IC to minimize the power loop area. A typical 0.1 µF decoupling capacitor is recommended to reduce the power loop area and any high-frequency components on VIN.
- The switching nodes (SW1 and SW2) have high-frequency voltage swings and should be kept at a small area. Keep analog components away from the SW1 and SW2 nodes to prevent stray capacitive noise pickup.
- Keep every power trace connected to the pin as wide as possible to improve thermal dissipation.
- The AGND pin is suggested to be connected to the 2<sup>nd</sup> GND plane through a via from the top to the 2<sup>nd</sup> layer.

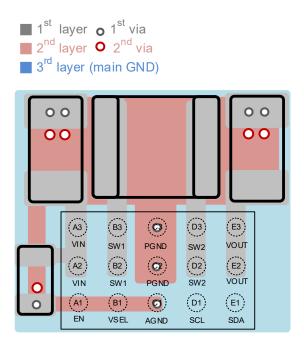


Figure 8. Layout Guide

- 1. The loop from VIN to CIN to PGND should be as short as possible to reduce the switching noise in buck mode.
- The loop from VOUT to COUT to PGND should be as short as possible to reduce the switching noise in boost mode.
- The loop from VIN to AGND should be separated from the PGND loop to reduce noise.
- Connect AGND directly to C3 or C2 to reduce noise.

Note 13. The information provided in this section is for reference only. The customer is solely responsible for designing, validating, and testing any applications incorporating Richtek's product(s). The customer is also responsible for applicable standards and any safety, security, or other requirements.



# 17 Functional Register Description

# 17.1 Register Table List

Name	Address	Description
CONTROL	0x01	Output pull-down slew rate control MODE function control DVS slew rate function control
STATUS	0x02	Read IC status
DEVID	0x03	Device identity
VOUT1	0x04	Output voltage 1 when the VSEL pin is low
VOUT2	0x05	Output voltage 2 when the VSEL pin is high

# 17.2 Register Description

 $I^2C$  Slave address = 1110101 (75H)

I<sup>2</sup>C Register Map

R: Read Only

RW: Read and Write

Address 0x01	CONTROL									
Bits	7	6	5	4	3	2	1	0		
Name	Reserved	I <sup>2</sup> C_SD	A_SLEW	Ultra-Sonic Mode	Forced PWM	Ramp PWM	DVS Slew Rate			
Reset	0	0	0	0	0	0	0	0		
Type	R	R/W	R/W	R/W	R/W	R/W	R/W	R/W		
Address 0x02				STA	TUS					
Bits	7	6	5	4	3	2	1	0		
Name		Reserved		HD	UV	ОС	TSD	PG		
Reset	0	0	0	0	0	0	0	0		
Type	R	R	R	R	R	R	R	R		
Address 0x03				DEVID						
Bits	7	6 5		4	3	2	1	0		
Name		Manu	facturer		M	lajor	Mir	nor		
Reset	1	0	1	0	1	0	1	1		
Type	R	R	R	R	R	R	R	R		
Address 0x04				VO	UT1					
Bits	7	6	5	4	3	2	1	0		
Name	Reserved				VOUT1					
Reset	0	0	1	1	0	0	1	1		
Type	R	R/W	R/W	R/W	R/W	R/W	R/W	R/W		
Address 0x05				VO	UT2					
Bits	7	6	5	4	3	2	1	0		
Name	Reserved				VOUT2					
Reset	0	1	0	0	1	0	0	1		
Туре	R	R/W	R/W	R/W	R/W	R/W	R/W	R/W		

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Address	Register Name	Bit	Bit Name	Default	Туре	Description
		7	Reserved	0	R	Reserved
		6:5	I <sup>2</sup> C_SDA_SLEW	00	R/W	SDA pin output pull-down slew rate 00: High (default) 01: Medium 10: Low 11: Very low
		4	Ultra-Sonic Mode	0	R/W	This bit controls the ultra-sonic mode function.  0: Ultra-Sonic mode disabled (default)  1: Ultra-Sonic mode enabled
0x01	CONTROL	3	Forced PWM	0	R/W	This bit controls the forced-PWM mode function.  0: Forced PWM operation disabled (default)  1: Forced PWM operation enabled
		2 Ramp PWM 0		0	R/W	This bit controls the ramp-PWM function.  0: Ramp-PWM operation disabled (default)  1: Ramp-PWM operation enabled
		1:0	DVS Slew Rate	00	R/W	These bits control the slew rate of the DVS function. 00: 1.0V/ms (default) 01: 2.5V/ms 10: 5.0V/ms 11: 10.0V/ms
		7:5	Reserved	000	R	Reserved
		4	HD	0	R	This bit shows the status of the hot-die function. 0: Normal operation (default) 1: A hot-die event is detected
		3 UV		0	R	This bit shows the status of the undervoltage function. 0: Normal operation (default) 1: An undervoltage event is detected
0x02	STATUS	2	00	0	R	This bit shows the status of the overcurrent function. 0: Normal operation (default) 1: An overcurrent event is detected
		1	TSD	0	R	This bit shows the status of the thermal shutdown function.  0: Temperature good (default)  1: An over-temperature event is detected
		0	PG	0	R	This bit shows the status of the power-good comparator. 0: Power-good (default) 1: A power-not-good is detected



Address	Register Name	Bit	Bit Name	Default	Туре	Description
		7:4	Manufacturer	1010	R	These bits identify the device manufacturer. 1010: Richtek (default)
0x03	0x03 DEVID	3:2	Major	10	R	These bits identify the major silicon revision. 00: A (initial silicon) 01: B (first major revision) 10: C (second major revision) (default) 11: D (third major revision)
		1:0	Minor	11	R	These bits identify the minor silicon revision. 00: 0 (initial silicon) 01: 1 (first minor revision) 10: 2 (second minor revision) 11: 3 (third minor revision) (default)
		7	Reserved	0	R	Reserved
0x04	VOUT1	6:0	VOUT1 0110011		R/W	These bits set the output voltage when the VSEL pin is low.  0000000: Vout = 2.025V  0000001: Vout = 2.05V  0000010: Vout = 2.075V  0110011: Vout = 3.3V (default)  1111101: Vout = 5.15V  1111111: Vout = 5.175V  1111111: Vout = 5.2V
		7	Reserved	0	R	Reserved
0x05	VOUT2	6:0	VOUT2	1001001	R/W	These bits set the output voltage when the VSEL pin is high.  0000000: Vout = 2.025V  0000001: Vout = 2.05V  0000010: Vout = 2.075V  1001001: Vout = 3.85V (default)  1111101: Vout = 5.15V  1111111: Vout = 5.175V  1111111: Vout = 5.2V



# Table 3. Register VOUT1/VOUT2[6:0] vs. Output Voltage

VOUT1 Address = 0x04, Output Voltage 1 when the VSEL pin is low.

VOUT2 Address = 0x05, Output Voltage 2 when the VSEL p

D! - 4	0.4
Register VOUT[6:0]	Output Voltage (V)
0000000	2.025
0000001	2.05
0000010	2.075
0000011	2.1
0000100	2.125
0000101	2.15
0000110	2.175
0000111	2.2
0001000	2.225
0001001	2.25
0001010	2.275
0001011	2.3
0001100	2.325
0001101	2.35
0001110	2.375
0001111	2.4
0010000	2.425
0010001	2.45
0010010	2.475
0010011	2.5
0010100	2.525
0010101	2.55
0010110	2.575
0010111	2.6
0011000	2.625
0011001	2.65
0011010	2.675
0011011	2.7
0011100	2.725
0011101	2.75
0011110	2.775
0011111	2.8

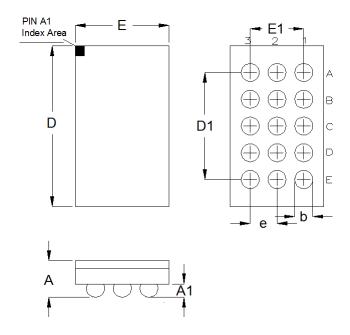
Register VOUT[6:0]	Output Voltage (V)
0100000	2.825
0100001	2.85
0100010	2.875
0100011	2.9
0100100	2.925
0100101	2.95
0100110	2.975
0100111	3
0101000	3.025
0101001	3.05
0101010	3.075
0101011	3.1
0101100	3.125
0101101	3.15
0101110	3.175
0101111	3.2
0110000	3.225
0110001	3.25
0110010	3.275
0110011	3.3
0110100	3.325
0110101	3.35
0110110	3.375
0110111	3.4
0111000	3.425
0111001	3.45
0111010	3.475
0111011	3.5
0111100	3.525
0111101	3.55
0111110	3.575
0111111	3.6

Register VOUT[6:0]	Output Voltage (V)
1000000	3.625
1000001	3.65
1000010	3.675
1000011	3.7
1000100	3.725
1000101	3.75
1000110	3.775
1000111	3.8
1001000	3.825
1001001	3.85
1001010	3.875
1001011	3.9
1001100	3.925
1001101	3.95
1001110	3.975
1001111	4
1010000	4.025
1010001	4.05
1010010	4.075
1010011	4.1
1010100	4.125
1010101	4.15
1010110	4.175
1010111	4.2
1011000	4.225
1011001	4.25
1011010	4.275
1011011	4.3
1011100	4.325
1011101	4.35
1011110	4.375
1011111	4.4

Register VOUT[6:0]	Output Voltage (V)					
1100000	4.425					
1100001	4.45					
1100010	4.475					
1100011	4.5					
1100100	4.525					
1100101	4.55					
1100110	4.575					
1100111	4.6					
1101000	4.625					
1101001	4.65					
1101010	4.675					
1101011	4.7					
1101100	4.725					
1101101	4.75					
1101110	4.775					
1101111	4.8					
1110000	4.825					
1110001	4.85					
1110010	4.875					
1110011	4.9					
1110100	4.925					
1110101	4.95					
1110110	4.975					
1110111	5					
1111000	5.025					
1111001	5.05					
1111010	5.075					
1111011	5.1					
1111100	5.125					
1111101	5.15					
1111110	5.175					
1111111	5.2					
1111011 1111100 1111101 1111110	5.1 5.125 5.15 5.175					



# **18 Outline Dimension**

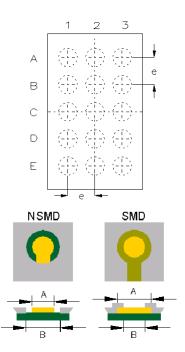


Sumbal	Dimensions I	In Millimeters	Dimensions In Inches			
Symbol	Min	Max	Min	Max		
Α	0.500	0.600	0.020	0.024		
A1	0.170	0.230	0.007	0.009		
b	0.240	0.300	0.009	0.012		
D	2.260	2.340	0.089	0.092		
D1	1.6	600	0.063			
E	1.360	1.440	0.054	0.057		
E1	0.8	300	0.031			
е	0.4	100	0.016			

15B WL-CSP 1.4x2.3 Package (BSC)



# 19 Footprint Information

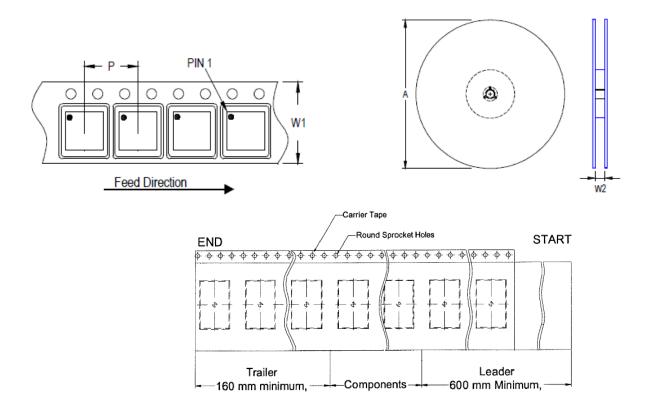


Dookogo	Number of Type		Footpri	Toloranco			
Package	Pin	Туре	e	Α	В	Tolerance	
\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	15	NSMD	0.400	0.240	0.340	±0.025	
WL-CSP1.4x2.3-15(BSC)	15	SMD	0.400	0.270	0.240	±0.025	

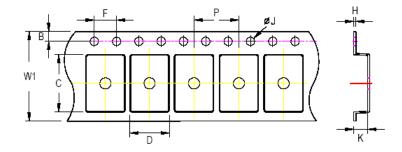


# 20 Packing Information

#### 20.1 **Tape and Reel Data**



Package Type	Tape Size (W1) (mm)	Pocket Pitch (P) (mm)	Reel Size (A) (mm) (in)						Units per Reel	Trailer (mm)	Leader (mm)	Reel Width (W2) Min/Max (mm)
WL-CSP 1.4x2.3	8	4	180	7	3,000	160	600	8.4/9.9				



C, D, and K are determined by component size. The clearance between the components and the cavity is as follows:

- For 8mm carrier tape: 0.5mm max.

Tono Cizo	W1	F	)	E	3	i	=	Q	Ŋ	ŀ	<	Н
Tape Size	Max	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	Max
8mm	8.3mm	3.9mm	4.1mm	1.65mm	1.85mm	3.9mm	4.1mm	1.5mm	1.6mm	0.7mm	0.8mm	0.6mm

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#### 20.2 **Tape and Reel Packing**

Step	Photo/Description	Step	Photo/Description
1	PICHTER TO A TO THE TOTAL TO TH	4	
	Reel 7"		12 inner boxes per outer box
2		5	RICHTEK INTRODUCE OF THE PROPERTY OF THE PROPE
	Packing by Anti-Static Bag		Outer box Carton A
3	RICHTERS AND THE STATE OF THE S	6	
	3 reels per inner box <b>Box A</b>		

Container	R	eel		Вох			Carton	
Package	Size	Units	Item	Reels	Units	Item	Boxes	Unit
WL-CSP	7"	2 000	Box A	3	9,000	Carton A	12	108,000
1.4x2.3	1	3,000	Box E	1	3,000	For Combined or Partial Reel.		



#### 20.3 **Packing Material Anti-ESD Property**

Surface Resistance	Aluminum Bag	Reel	Cover tape	Carrier tape	Tube	Protection Band
$\Omega$ /cm <sup>2</sup>	10 <sup>4</sup> to 10 <sup>11</sup>					

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21 Datasheet Revision History

Version	Date	Description		
01 2023/7/7		Ordering Information on P2 Electrical Characteristics on P5 Application Information on P16 Packing Information on P29, 30, 31		
02	2025/11/12	Changed the name of pin B2 and pin B3 to SW1; pin D2 and pin D3 to SW2.  Application Information on page 26  - Modified layout guide  Packing Information on page 33  - Updated Tape and Reel Data		